

Supplement: Comparison between Dirac's $\langle \text{Bra} | \text{Ket} \rangle$ Notation and Einstein's Σ ummation Convention

Quantity	Dirac's $\langle \text{Bra} \text{Ket} \rangle$ Notation	Einstein Σ ummation Convention
abstract vector in vector space \mathbb{M}	$ x\rangle$ ket \Updownarrow clear difference	x “=” \vec{x} column vector \Updownarrow no clear distinction
abstract vector in dual space $\overline{\mathbb{M}}$	$\langle x $ bra	x “=” \vec{x}^T row vector (when x real; otherwise “=” \vec{x}^\dagger)
basis of \mathbb{M}	$ i\rangle, i = 1, \dots, \dim\mathbb{M}$ no distinction betw. basis & vectors kets can be basis vectors	$e_i, i = 1, \dots, \dim\mathbb{M}$ clear separation of vector components and basis
basis of $\overline{\mathbb{M}}$	$\langle i , i = 1, \dots, \dim\overline{\mathbb{M}}$	$\epsilon^i, i = 1, \dots, \dim\overline{\mathbb{M}}$
ortho-normality	$\langle i j\rangle = \delta_{ij} \forall i, j = 1, \dots, \dim\mathbb{M}$ if $\overline{\mathbb{M}} \simeq \mathbb{M}$	$\langle \epsilon^i e_j \rangle = \delta_j^i$
closure/completeness	$\sum_i i\rangle\langle i = \text{id}$ ”inserting unity”, used often	$\epsilon^i \otimes e_i = 1$ tensor product, used infrequently
scalar product $\langle y, x \rangle$ of $x \in \mathbb{M}$ and $y \in \overline{\mathbb{M}}$	$\langle y x\rangle = (\langle x y\rangle)^*$ usually complex	$y_i x^i = y^i x_i$ usually real
metric $g_{ij} =$???	$\langle e_i, e_j \rangle$
contravariant components	$\langle i x\rangle$	x^i
covariant/dual components	$\langle x i\rangle$	x_i
relation between the two	$\langle x i\rangle = (\langle i x\rangle)^*$	$x_i = g_{ij} x^j$
basis change	$\langle n x\rangle = \sum_j \langle n j\rangle \langle j x\rangle$	$\tilde{x}^i = d^i_j x^j$
components of matrix M	$\langle i M j\rangle$	M^i_j (index ordering important)
abstract matrix $M =$ from components	$\sum_{ij} i\rangle \langle i M j\rangle \langle j $	$e_i M^i_j \epsilon^j$
Further typical features	prefers abstract vectors e.g. “states” in QM can deal with infinite-dim. space and continuous basis can deal with complex components non-orthogonal bases hard to describe order matters: $ i\rangle \langle j \neq \langle j i\rangle$ no summation, e.g. projector on eigenstate: $ i\rangle \langle i \neq \sum_i i\rangle \langle i = \text{id}$ ambiguous operator action $\langle y Mx\rangle \stackrel{?}{=} \langle My x\rangle \stackrel{?}{=} \langle y M x\rangle$ e.g. selfadjoint vs. Hermitean	prefers concrete representations e.g. locally orthog. coord., GRT prefers finite-dim. space prefers real components made for non-orthogonal bases & metrics components commute: $x_i y^j = y^j x_i$ summation “mandatory” operator action cannot be addressed