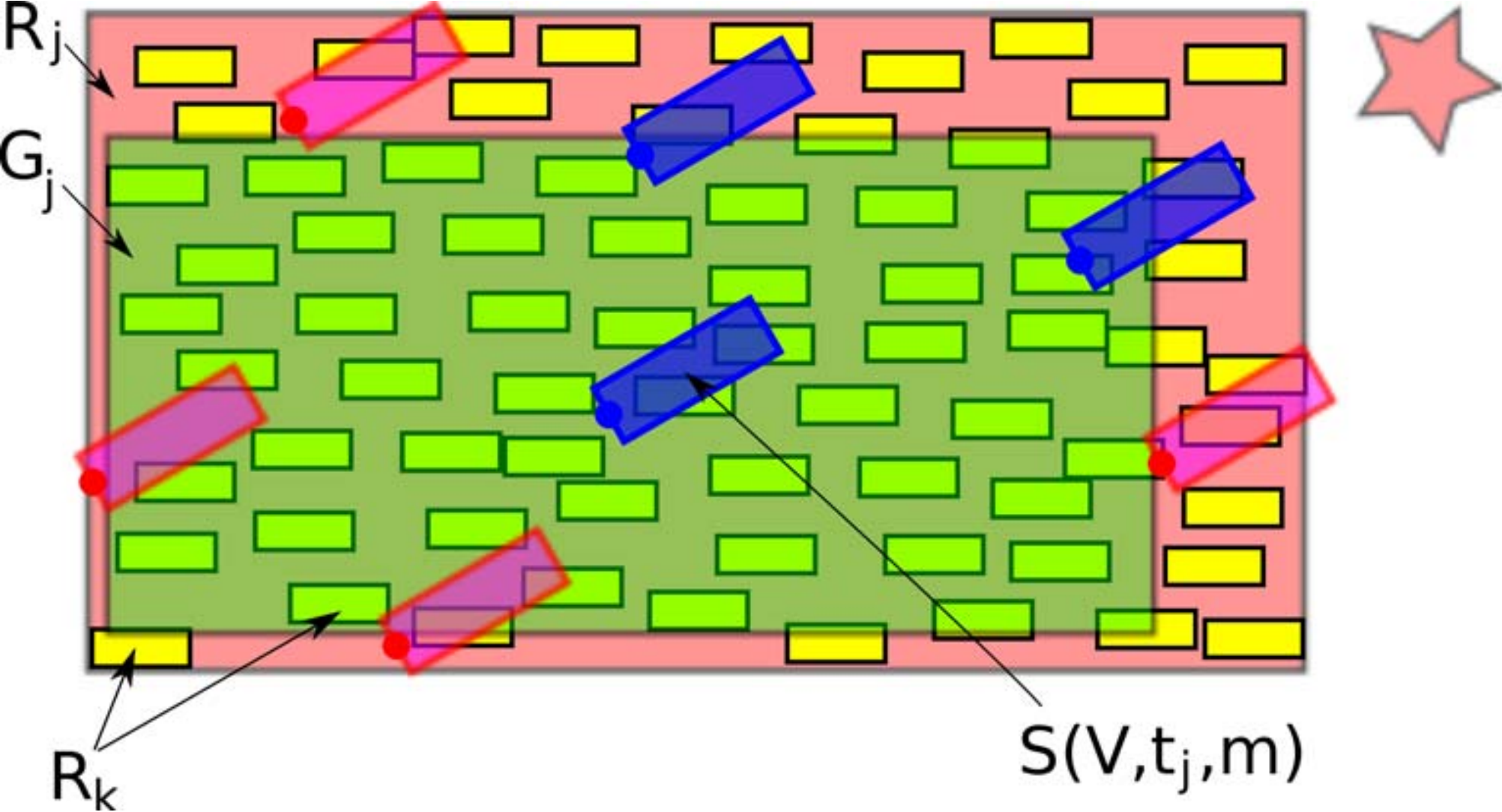
R_j
G_j
R_k
$S(V,t_j,m)$